



System 1: Four measures of music. The first staff contains notes with articulation marks (vertical lines) above them. The second staff contains notes with accents (gamma symbol) above them. The third staff contains notes with dynamic markings (f, s) below them. The fourth staff contains notes with dynamic markings (f, m, d) below them.

Notes: d', d', d', d', d', d', d', d', r, l, d', d', d', d', d', d', d', m, s, s

Accents: γ, γ, γ, γ, γ, γ, γ, γ, γ, γ, γ, γ, γ, γ, γ, γ, γ, γ

Dynamics: f, d, f, d, m, d, m, d

System 2: Four measures of music. The first staff contains notes with articulation marks above them. The second staff contains notes with accents above them. The third staff contains notes with dynamic markings (d', s, l, f, t) below them. The fourth staff contains notes with dynamic markings (m, r, f, m, s, r, f, d) below them.

Notes: s, f, l, l, s, d', t, t, l, s, f, l, l, s, f, m

Accents: γ, γ, γ, γ, γ, γ, γ, γ, γ, γ, γ, γ, γ, γ, γ, γ, γ, γ

Dynamics: d', s, d', s, l, f, t, s, t, s, l, f, l

Dynamics: m, r, f, m, s, r, f, d

System 3: Four measures of music. The first staff contains notes with articulation marks above them. The second staff contains notes with accents above them. The third staff contains notes with dynamic markings (d', s, l, f, t) below them. The fourth staff contains notes with dynamic markings (m, r, f, m, t, l, t, l) below them.

Notes: s, f, l, l, s, d', t, t, s, l, d', t, t, s, l, d'

Accents: γ, γ, γ, γ, γ, γ, γ, γ, γ, γ, γ, γ, γ, γ, γ, γ, γ, γ

Dynamics: d', s, d', s, l, f, t, s, l, f, t, l, t, l

Dynamics: m, r, f, m, t, l, t, l

System 4: Four measures of music. The first staff contains notes with articulation marks above them. The second staff contains notes with accents above them. The third staff contains notes with dynamic markings (t, m) below them. The fourth staff contains notes with dynamic markings (m, m) below them.

Notes: t, m, m, m, m, m, m, m, m, m, m, m, m, m

Accents: γ, γ, γ, γ, γ, γ, γ, γ, γ, γ, γ, γ, γ, γ

Dynamics: t, m, t, m, t, m, t, m, t, m, t, m, t, m

Dynamics: m, m, m, m, m, m, m, m, m, m, m, m, m, m